

Experimental investigation on scheduling tasks through Greedy Algorithm

Nageswara Rao Medikundu

Department of Mechanical Engineering, Koneru Lakshmaiah Education Foundation, Vaddeswaram, Guntur,
Andhra Pradesh, India-522302

E mail: medikundu1979@gmail.com

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Abstract. substantial research has been conducted on flexible manufacturing systems (FMS) planning, it has predominantly centred on well-established academic layout strategies. The selection process primarily relies on fundamental principles within the intelligent system JSSE (workshop scheduling environment), with limited literature available on its application within an FMS. This article aims to investigate the performance of machine and AGV (Automated Guided Vehicle) scheduling models in reducing the number of operations within the FMS using a Greedy Algorithm (GA) approach. The methodology is evaluated under various experimental conditions through an FMS simulation model encompassing 40 different scenarios.

Keywords: Artificial Neural Network, Task scheduling, Artificial intelligence and Makespan

1. Introduction

Decision-making rules are widely employed today, and applications range from online scheduling of machines and material handling devices under real operating conditions to offline scheduling algorithms with integrated components. Panwalkar and Iskander (1977) documented over 100 rules, distinguishing between scheduling rules, dispatching rules, and priority rules. Further literature on these rules can be found in works by Conway et al. (1967), Blackstone et al. (1982), Kiran and Smith (1984a, b). Scheduling rules are utilized to prioritize machines and AGVs based on completion times, including travel times. Egbelu and Tanchoco (1984) proposed scheduling rules for dispatching AGVs, while Acree and Smith (1985) explored selection rules in FMS. Recent research trends are geared toward the implementation of intelligent systems in scheduling problems as opposed to traditional job shop scheduling, compared to experimental studies in FMS (Sabuncuoglu and Hommertzhaim 1989b). Stecke and Solberg (1981) examined heuristic rules in FMS with ten machines and two AGVs, while Denzler and Boe (1987) delved into AGV routing, including operation time data, with experimental investigations of FMS. Choi and Malstrom (1988) addressed the FMS scheduling model, focusing on a small closed-loop FMS with two microcomputers and formulated two rules related to part and machine selection. Montazeri and Wassenhove (1989) conducted an investigation of several rules for FMS performance. Co et al. (1988) presented scheduling rules for a closed-loop FMS, concluding that not all scheduling rules are critical in a job shop scenario. Egbelu and Tanchoco (1984) studied the scheduling of AGVs and machines, emphasizing that finding the best cart selection rule was challenging. In conclusion, Sabuncuoglu and Hommertzhaim (1989a) developed scheduling rules based on their study, highlighting the importance of AGVs scheduling over machine scheduling. To gain a better understanding, FMS scheduling problems are addressed using scheduling rules under different conditions, encompassing material handling and machine aspects. These rules can be classified into two categories: scheduling of machines and scheduling of AGVs. Among these, the Greedy Algorithm (GA) rule stands out as a fundamental approach to job completion, especially when considering high AGV speeds.

2. Greedy Algorithm Design

The input data for this study is derived from the research conducted by Bilge and Ulusoy in 1995. This dataset includes information on a series of machines, their respective processing times, and a matrix representing the travel times between these machines. The configuration, as depicted in Figure 1, involves four CNC machines that are equipped with pallet changers and a set of tools.

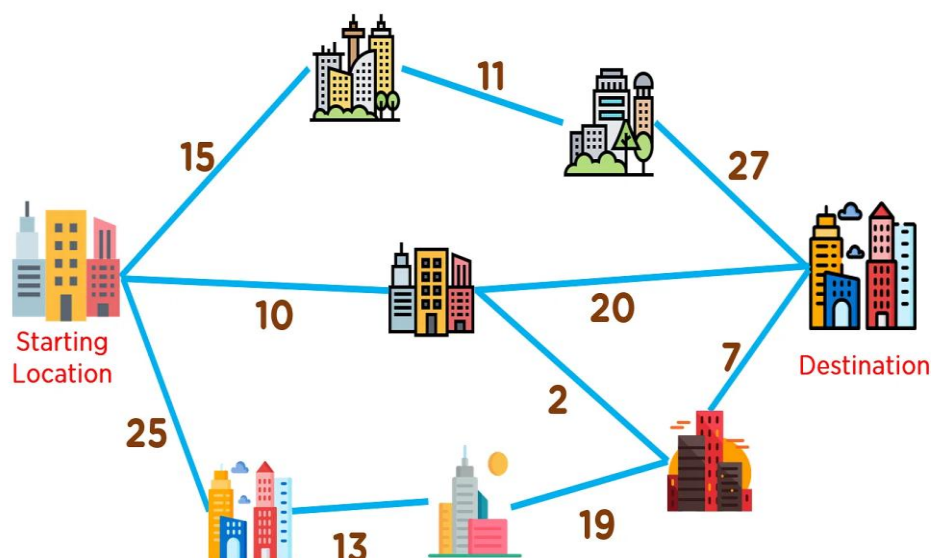


Figure 1: Basic structure of Greedy Algorithm

2.1. Methodology

Layout 2 and Job set 5 play a crucial role in the execution of the Greedy Algorithm (GA) as an example with half the movement time and double the process time. The GA is explained in the following steps for Job Set 5:

Step 1: Consider Job Set 5. Step 2: Initially, place item '1' at the beginning of the primary line, arranged as follows: 1 – 2 - 3 - 4 - 5 - 6 - 7 – 8 – 9 – 10 - 11 - 12 - 13. Step 3: Determine the maximum completion time, representing the possible completion time (makespan) for the given job set.

Table 1 displays the specific constraints for all the activities involved in the GA:

Table 1. Completion Time Using GA

Order	Machine	Operation	TT	JRT	Job Reach Time	Process Time	Makespan
1	1	1	0	3	2	6	14
2	2	2	27	30	15	12	39
3	4	1	78	82	41	9	59
4	1	2	35	38	21	18	57
5	3	2	98	102	59	6	71
6	2	1	132	135	77	15	107
7	3	2	106	111	71	9	89
8	4	2	168	171	90	3	96
9	1	1	195	200	100	12	124
10	4	2	174	180	96	6	108
11	2	2	237	241	113	15	143
12	3	1	103	107	107	3	113
13	1	1	113	118	124	9	142

Table 1 illustrates the activity scheduling through the GA algorithm for Job Set 5, resulting in a total completion time (makespan) of 143.

Total completion time = 1162

Average flow time = Total completion time / Total number of operations = $1162 / 13 = 89.38$ Average number of operations in the FMS = Total Flow Time / Makespan = $1162 / 143 = 9$

3. Results and Discussion

The results must be presented in a clear and concise manner, focusing on the most significant or primary findings of the research. In the discussion section, it is essential to delve into the importance of the research outcomes.

The workshop scenario described for Flexible Manufacturing Systems (FMS) involves the utilization of Job Set Model 5 and Layout 2

Problem. No	Lay out	No of Operations in Greedy System
P1	1	7
P 2	1	8
P 3	1	8
P 4	1	10
P 5	1	8
P 6	1	10
P 7	1	10
P 8	1	11
P 9	1	9
P 10	1	11
P1	2	7
P 2	2	8
P 3	2	8
P 4	2	10
P 5	2	8
P 6	2	10
P 7	2	10
P 8	2	11
P 9	2	9
P 10	2	11
P1	3	7
P 2	3	8
P 3	3	8
P 4	3	10
P 5	3	8
P 6	3	10
P 7	3	10
P 8	3	11
P 9	3	9
P 10	3	12
P1	4	7
P 2	4	8
P 3	4	8
P 4	4	10
P 5	4	7
P 6	4	10
P 7	4	17
P 8	4	11
P 9	4	9
P 10	4	11

In the context of optimizing the arrangement of Automated Guided Vehicles (AGVs) and machines, priority rules are employed to manage three distinct processing time values. These rules are outlined in

two separate tables. An analysis of the makespan and mean flow time across different job sets and layouts is visually represented in Figures 2.

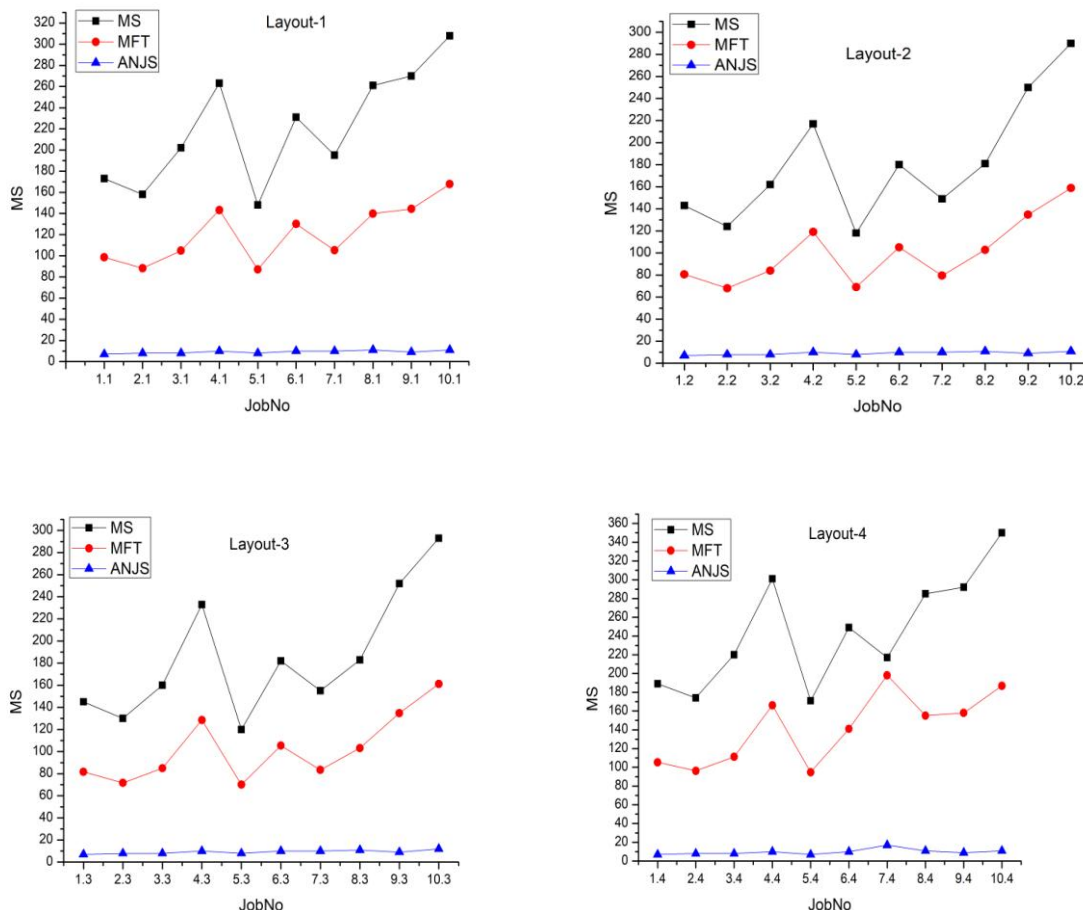


Figure 2: Make span Vs Mean flow time ($t/p < 0.25$)

4. Conclusions.

FMS problems are addressed using a Greedy Algorithm (GA) aimed at minimizing the number of operations within a system containing four layouts, each equipped with four identical machines and two material handling systems. This study encompasses not only machine scheduling but also the scheduling of Automated Guided Vehicles (AGVs), with the following results: The research indicates that an increase in the number of jobs within the system leads to a corresponding rise in machine and AGV utilization. Notably, the distribution of completion times in the FMS is greatly influenced by the number of operations in the system. When both AGV and machine loads increase due to scheduling rules, the number of operations in the system becomes crucial as it directly impacts the overall utilization of the FMS. This, in turn, results in an increase in job tardiness. The GA rule was tested with a system involving 40 operations, and it consistently outperformed other approaches, including AGV-based rules. Future endeavours should focus on the development and implementation of new rules within the FMS environment, allowing for continuous testing with various objective functions.

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